Optical Belt Scale

Instalation & User Manual

! Attention, important safety advice!

Do not switch on the sensor until it is completely mounted on the machine and the laser sources are aligned to the conveyor. The switched on sensor sends invisible laser radiation during the measuring procedure. The sources of laser are activated only when the conveyor is moving. This condition is indicated by the blinking red signal lamp.

When the conveyor is not moving, the sources of laser are switched off automatically. This state is indicated by the red signal lamp with a short flashing signal, followed by a long pause.

However, to guarantee maximum safety, it should be always avoided to look directly into the optical outlets while the sensor is currently supplied.

Welding current flowing through the sensor unit causes damage to the Optical Belt Scale!
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1 Extent of delivery

Sensor Unit

CAT B15Q Mobile Phone, Charger unit 110/220V, USB/charging cable, USB Charger unit for 12V/24V

Thermal Printer + charger unit 110/220V + thermal paper

Frame & Bolts
Inductive sensor + Support bracket for the inductive sensor

Inductive sensor cable 0.5m + Inductive sensor cable 2.5m

Power cable 2.5m + 15m

Optional DC/DC Converter 12V/24V 10A + Cables

Technical Data
U In: 11V ... 14.5V
U Out: 24V, limited to 26V
I Out: 6A
2 Installation of the Optical Belt Scale System

2.1 Installing the inductive proximity switch sensor

The inductive sensor is there to measure the drum speed and has to be mounted in a good position on the drive pulley of the belt conveyor. (see picture for better understanding)

The inductive sensor on the bracket and the impulse sensor on the conveyor drum shaft must be aligned that they pass each other in a distance of 3–5 mm [0,18 - 0,197 inch]
2.2 Connecting the Power Supply Cable

Connect the power supply cable (Cable D) to the power source. The optical belt scale needs 24V DC 5 A power source.

<table>
<thead>
<tr>
<th>Power supply cable D</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Pin 1 / brown wire</td>
<td>+24V DC</td>
</tr>
<tr>
<td>Pin 2 / blue wire</td>
<td>-24V DC (GND)</td>
</tr>
</tbody>
</table>

2.3 Mounting of Sensor Unit

The sensor is bolted on the frame with 6 pieces M8 hex bolts which are supplied with the unit.

Be sure to not exceed the maximum mounting height of 600mm [23.622 inch]. A mounting position on 600 mm [23.622 inch] distance allows to measure material with height of 400mm [15.758 inch] on the belt. If the mounting height falls below 600mm [23.622 inch], it will narrow the full measuring range.

After powering on the sensor, two red laser dots will be visible for about 5 minutes. Use these two dots, which are marking the active measuring line to position the sensor accordingly the pictures.

To power on the sensor connect the power supply cable C to the sensor and to the power supply cable D

The sensor has to be on the apex of the roller. Use the two red laser dots (one on each side of the sensor) to check whether they match the point of contact between belt & drum exactly!

Also be sure to pay attention to the running direction of the conveyer!
The sensor has to be mounted in the right direction!
Sensor over discharge drum

Sensor over roller station
The following table shows, which sensor fits best to each conveyor belt width.

<table>
<thead>
<tr>
<th>Sensor</th>
<th>Conveyor belt width [mm]</th>
<th>Conveyor belt width [inch]</th>
</tr>
</thead>
<tbody>
<tr>
<td>600</td>
<td>400 – 600</td>
<td>15.7 – 23.6</td>
</tr>
<tr>
<td>800</td>
<td>600 – 800</td>
<td>23.6 – 31.5</td>
</tr>
<tr>
<td>1000</td>
<td>800 – 1000</td>
<td>31.5 – 39.4</td>
</tr>
<tr>
<td>1200</td>
<td>1000 - 1300</td>
<td>39.4 – 51.2</td>
</tr>
<tr>
<td>1400</td>
<td>1300 - 1600</td>
<td>51.2 - 63.0</td>
</tr>
</tbody>
</table>

ATTENTION:
If the red laser beams are on the side stripper, then they have to be cut out! The side strippers should be cut like on the pictures!
2.4 Connecting the cables of the system

Connect the inductive sensor to the measuring sensor using the data cable A & B. The sensor is then connected to 24 V DC / 5 A power source using the power supply cables C & D. If the sensor is used in conjunction with a 12 Volt powered system, the DC/DC converter E has to be used. It is advised to connect the sensor to the power supply at the ignition so that the sensor is only turned on when the ignition is on and the plant is running.

Following please find the occupancy of the cable D:

<table>
<thead>
<tr>
<th>Power supply cable D</th>
<th></th>
</tr>
</thead>
<tbody>
<tr>
<td>Pin 1 / brown wire</td>
<td>+24V DC</td>
</tr>
<tr>
<td>Pin 2 / blue wire</td>
<td>-24V DC (GND)</td>
</tr>
</tbody>
</table>

You must take care when mounting all the cables to ensure that they can’t be damaged or squashed when the plant is working or when the plant is being transported i.e. the conveyors are folded.
3 Getting Started with the Mobile Phone

3.1 Inserting the battery

1. Slide the back cover latch to the unlock position.

2. Hook your fingertip under the back cover.

3. Pry to open the back cover.

4. You now have access to battery compartment. Insert the battery. Make sure the contacts of the battery are aligned with the connectors in the battery compartment.

5. Make sure the rear cover is the correct way round.

6. Engage the hooks on the top of the back cover with the designated holes on your phone.
7. Push the back cover firmly to secure it into place. Note: Be careful not to bend the lugs/catches/hooks on the battery cover.

8. Press and hold the bottom of the back cover and slide the back cover latch to the left to lock the back cover.

3.2 Powering on the Mobile Phone

To power on press the Power button.

Key functions at your fingertips:

**Power button:** Press to turn on your mobile phone. Press and hold to open the Phone options menu. Press to lock or wake the screen when your mobile phone is on.

**Home key:** Press at any time to display the Home screen. A long press of the Home key will launch Google search or Google Now.
Menu key: Touch to open a menu with options that relate to the current screen or application.  
A long press of the Menu key will list the recent applications used.  
A short press of the Menu key from the Home screen will display all screen and icon settings.

Back key: Touch to display the previous screen you were working in.  
Use to close onscreen keyboard.

3.3 Set User Interface Language

1 touch to display all apps
2 swipe to the next page
3 touch “Settings”
4 scroll down
5 touch “Language & input”
6 touch “Language”
7 select your Language
8 touch here to go back
3.4 Set Date & Time

1. Touch “Date & time”
2. Touch “Automatic date & time”
3. Select “Off”
4. Touch “Set date”
5. Set date and touch “Done”
6. Touch “Set time”
7. Set time and touch “Done”
8. Uncheck “Automatic time zone”
9. Touch “Select time zone”
10. Select your time zone
11. Touch the “Home key” to display the home screen

4 Start of SensorManager Application

1. Touch “SensorManager” icon to start the App
2. Touch “Allow” to turn on Bluetooth
3. Turning Bluetooth on

Bluetooth Connection Indicator
GREEN = connected
RED = disconnected
4.1 Connecting to Sensor Unit

If Android asks for a pairing code for the Sensor then use following Bluetooth pairing code: **hsbt00000**

1. Touch “Connect wireless”
2. Touch “Scan for devices”
3. Select “Sensor_XXX”
4. Connecting to “Sensor_XXX”

Bluetoop Connection Indicator
- GREEN = connected
- RED = disconnected

4.2 Setting Time & Date of Sensor Unit

1. Touch “System Settings”
2. Touch “Clock”
3. Touch “Set Sensor Clock”
4. Touch “Check Sensor Clock”
5. Confirm with “OK”
6. Touch “Check Sensor Clock” It shows the actual time & date on sensor unit
7. Check if the time & date is actual and confirm with “OK”
4.3 Configuration of Drum Diameter

The most accurate way to determine the roll diameter is to measure the perimeter of the drum and acquire the diameter mathematical by dividing with Pi (3,14). The diameter includes the rubber coating of the roll, but does not include the conveyor belt.

4.4 Calibration Run

Hint: prior to the start of a new calibration run please ensure that the SensorManager is connected to the sensor!

It has to be ensured, that the EMPTY conveyor belt is running at working speed (sensor has to be in measuring state, red signal lamp is blinking once per second).

The conveyor belt must be clean and free from deposits of feeding material.
When a calibration run has been started, the red signal lamp starts to flash with fast repetition followed by a short period of steady burning signal lamp. The calibration run is finished when the sensor enters its measuring state with the red signal lamp blinking every second once.

4.5 Input Master Data

If customer or material name are not yet listed in the master data, the data record has to be added.

First of all we have to choose the group in which the new data record is to be added. (Customer or Material)

Now a description can be added to the text field by using the displayed On Screen Keyboard.

By clicking the “Add” button, the new description is added to the list.

We can change back to the main menu by clicking the confirmation symbol in the bottom right corner.
4.6 Start New Measurement

To start a new measurement with the new entered customer name and material name you have to select once those and touch the “Start new measurement” button.

Now the sensor will remember the configuration and will measure the further measurements with this configuration till you changing it.
5 Adjusting
For the measuring adjustment you will need a truck like on the next picture or a container.

The capacity of the container or the truck must be at least 7m³. Measure the distances a, b and c.

Calculate the volume of the container: \( V = a \cdot b \cdot c \)

5.1 Start test measurement
To ensure a good average of the test you have to measure 3 times.

Ensure that you have started a new measurement and the span adjustment factor of the material is set to 100 % and it keeps stable at 0 m³ on a empty running belt. (how to set the span adjust see chapter 5.2)

Start feeding material and fill up the container (truck) till it is full. flatten the material in the container. Make sure that the material is not compressed during flattening.
After the known volume of material has run through the sensor and you have measured 3 times, you should have 4 values at hand.

*ContainerVolume* = the volume of the container

*Volume 1* = the value shown on SensorManager after 1st measurement  
*Volume 2* = the value shown on SensorManager after 2nd measurement  
*Volume 3* = the value shown on SensorManager after 3rd measurement

*TotalAverage* = average of the 3 measurements.

The average value is calculated using the following formula:

\[
\text{TotalAverage [m3]} = \frac{(\text{Volume1} + \text{Volume2} + \text{Volume3})}{3}
\]

The span adjust factor is calculated using the following formula:

\[
\text{span adjust [\%]} = 100 + \left( \frac{\text{ContainerVolume} - \text{TotalAverage}}{\text{TotalAverage} \times 100} \right)
\]

Example:

ContainerVolume = 10m³  
Volume1=10,34  
Volume2=10,30  
Volume3=10,2

\[
\text{SensorManagerTotalAverage [m3]} = \frac{(10,34 + 10,30 + 10,20)}{3} = \frac{30,84}{3} = 10,28m³
\]

\[
\text{span adjust factor [\%]} = 100 + \left( \frac{10 - 10,28}{10,28/100} \right) = 100 + \frac{-0,28}{0,1028} = 100 - 2,7 = 97,3 \approx 97\%
\]
5.2 Setting the span adjust

To enable the span adjust register page, connect to the sensor, go to system settings and login as administrator. Default (factory set) password is “0000”.

1. Touch “System settings”
2. Select “admin” tab
3. Touch “Login”
4. Tap into the input field
5. Type in the default password: 0000
6. Confirm with “OK”
7. Long click onto the yellow key icon
8. Tap into the input field
9. Type in: 4957
10. Confirm with “OK”
11. Type in 1 to activate
12. Confirm with “OK”
13. Touch “Main menu”
14. Touch “Input master data”
15. Scroll to the left by swiping
16. Select “SPAN ADJUST” tab
17. Select the material
18. Select material
19. Change the value by scrolling up or down
20. Touch “Apply” to confirm the value
Now you can do a control measurement to check the measured volume. If you have still difference between the measured volume and the real volume, then you have to repeat the adjustment.

These steps must be repeated on every different material.

6 Measurements

6.1 Print measurements
6.2 Print downloaded measurements

1 Touch “Print”

2 Select “No”

3 Select data file

4 Tap on a measurement to select

5 Selects all measurements on same day

6 Number of copies to print

7 Confirm to show the preview

8 Select “Print”

9 Power on printer and select “OK”

10 Connecting to the printer and printing

11 Reconnected to the sensor unit
6.3 Send measurements as e-mail attachment

1. Touch e-mail button
2. Select data file to send
3. Confirm
4. Select your e-mail app to send. Here Gmail
5. Type in recipients e-mail address
6. Touch send icon to send
7. Sends e-mail & returns to main menu

6.4 View downloaded measurement as Excel spreadsheet

1. Touch XLS button
2. Select data file to view
3. Confirm
4. Select your office app to view XLS-file. Here WPS.
5. Select “Just once”
6.5 Location of exported XLS-File on the mobile phone

1. touch to display all apps
2. select File Manager
3. touch “Phone storage”
4. touch “Download”
5. measurement files name format: data_Sensor_###.xls
   ###: number of the sensor

6.6 Copying the XLS-file to your desktop over USB-Cable

1. connect your mobile phone with the supplied usb-cable
2. start “Windows Explorer”
3. expand “Computer”
4. click onto “CatB15Q”
5. double click onto “Phone storage”
6. double click onto “Download”
7. copy the file & paste it to your desktop
7 System Settings

7.1 Admin(Login/Logout)

7.1.1 Change Login Password

1. Touch “Login”
2. Tap into the input field
3. Type in the default password: 0000
4. Confirm with “OK”
5. You are logged in

1. Touch “Change password”
2. Tap into the input field
3. Type in the new password
4. Confirm with “OK”
5. Type in the new password again for confirmation
6. Confirm with “OK”
7. Confirm with “OK”
8. The password is changed now

7.2 Configuration
See chapter 4.3

7.3 Clock
See chapter 4.2
7.4 Language

1 touch “Language”

2 touch “Change Language”

2 scroll and select your language. This changes the UI-Language of Android and if your language is not available in SensorManager-App, then English will be used in the App. The UI-Language of Android will be displayed in the selected language.

7.5 Memory

1 touch “Memory”

99% of the memory are still free

7.5.1 Clear Memory

1 touch “Clear Memory”

2 select “OK”

3 select “OK”

4 touch “Memory”

5 100% free memory is shown

When the memory is cleared a backup file is stored from the data which were downloaded on to the mobile phone.

Hint: Be sure that you have downloaded all measurements before clearing memory!
7.6 Units

1. Touch "Units".
2. Tap on to the selection list.
3. Select the unit "t" as an example.
4. Confirm.
5. The unit is now "t".
6. The spec. weight of the material will be displayed here.

---

7.6.1 Setting the specific weight of a material

Be sure that you are logged in!

1. Touch "Input master data".
2. Scroll to the left by swiping.
3. Select "SPECIFIC WEIGHT".
4. Select the material.
5. Tap to edit.
6. Type in the new value.
7. Touch enter.
8. Touch "Apply" to confirm.
9. Touch "OK".
10. Touch "Apply" to save.
11. Data are sending.
12. Touch "New Measurement".

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7.7 Print-Settings

- Sensor name will be printed
- Customer name will be printed
- Material name will be printed
- Specific weight will be printed

Print head editor: Max. 5 lines of text can be printed out

7.8 Pairing & Selecting the printer

1 touch “Print”
2 power on the printer
3 touch “Scan for devices”
4 wait till DPP-250 is listed
5 select DPP-250

14 select customer
15 select material
16 touch “Start new measurement”
17 now it’s measured with the new spec. weight value
7.9 System

7.10 Diagnostic report

Hint: If a pairing code is requested then use following PIN-code: **0000** for Bluetooth pairing

6 the printer is paired and selected

1 touch “diagnostic report”

2 wait

Sensor name
Firmware version
Parameter list. Scroll up to see all values.

3 close with “OK”

SensorManager version
8 Thermal Bluetooth Printer

8.1 Loading paper

The DPP-250 uses a drop-and-load design making paper loading easy and trouble free. To load paper, simply lift up the paper cover latch and drop in the new roll as shown in the steps below.

1. Slide the paper cover latch to unlock the paper cover as shown in the figure.
2. Lift the paper cover latch to open the paper cover as shown in the figure.
3. Insert the new roll of thermal paper roll as shown in the figure. Be sure to pull at least 12 mms or more of paper above the top of the printer before closing. Close the paper cover until it snaps lock. Slide paper cover latch to lock the cover in place.
9 Safety Instructions Laser Class

9.1 Laser Class of Device
According to IEC 60825-1:2007 the sensor is classified as laser equipment of class 3B. Invisible laser radiation is emitted.

- Pulse output: \( P_{\text{max}} = 60 \text{ mW} \)
- Pulse duration: \( t_{\text{pulse}} = 400 \text{ µs} \)
- Wavelength: \( \lambda = 785 \text{ nm} \)
- Pulse repetition rate: \( f_{\text{rep}} = 200 \text{ Hz} \)

9.2 Warning
Laser radiation of class 3B is emitted as soon as the device is working!

Therefore, the following items must be ensured before starting up the device:

- The sensor may only be started, if it is duly attached at the sensor mounting. Otherwise all persons concerned must wear safety goggles.
- Strip run must not be simulated.
- The optical path must be terminated in case of lack of measuring stock!
- There must not be any reflecting surfaces mounted in the optical path that might lead to reflections! (For optical path see Fig. 5).
- During operation the operating personnel and other persons must not look directly into the emitted beams!
- The safety instructions demanded in the standard for the use of devices of laser class 3B must be complied with.

The following warning signs must be applied at the device:

10 Servicing and cleaning
The sensor is usually service free, only from time to time lenses and windows must be cleaned. They can be cleaned with a cotton cloth.

**WARNING!**

- DO NOT USE A HIGH-PRESSURE CLEANER! THE SENSOR IS NOT HIGH-PRESSURE PROOF!
11 Spare parts
<table>
<thead>
<tr>
<th>Position</th>
<th>Art. Nr.</th>
<th>Beschreibung</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>150600</td>
<td>Optical Belt Scale S600</td>
</tr>
<tr>
<td>1</td>
<td>150800</td>
<td>Optical Belt Scale S800</td>
</tr>
<tr>
<td>1</td>
<td>151000</td>
<td>Optical Belt Scale S1000</td>
</tr>
<tr>
<td>1</td>
<td>151200</td>
<td>Optical Belt Scale S1200</td>
</tr>
<tr>
<td>1</td>
<td>151400</td>
<td>Optical Belt Scale S1400</td>
</tr>
<tr>
<td>1</td>
<td>150604</td>
<td>Optical Belt Scale -MultiLink ML600</td>
</tr>
<tr>
<td>1</td>
<td>150804</td>
<td>Optical Belt Scale -MultiLink ML800</td>
</tr>
<tr>
<td>1</td>
<td>151004</td>
<td>Optical Belt Scale -MultiLink ML1000</td>
</tr>
<tr>
<td>1</td>
<td>151204</td>
<td>Optical Belt Scale -MultiLink ML1200</td>
</tr>
<tr>
<td>1</td>
<td>151404</td>
<td>Optical Belt Scale -MultiLink ML1400</td>
</tr>
<tr>
<td>2</td>
<td>151205</td>
<td>Frame high for 600-800mm</td>
</tr>
<tr>
<td>2</td>
<td>150601</td>
<td>Frame high for 1000-1200mm</td>
</tr>
<tr>
<td>2</td>
<td>151401</td>
<td>Frame high for 1400-1600mm</td>
</tr>
<tr>
<td>2</td>
<td>151203</td>
<td>Frame low for 600-800mm</td>
</tr>
<tr>
<td>2</td>
<td>151201</td>
<td>Frame low for 1000-1200mm</td>
</tr>
<tr>
<td>2</td>
<td>151208</td>
<td>Frame low for 1400-1600mm</td>
</tr>
<tr>
<td>3</td>
<td>110030</td>
<td>Power supply cable 2,5m</td>
</tr>
<tr>
<td>3</td>
<td>110130</td>
<td>Power supply cable 2,5m-MultiLink</td>
</tr>
<tr>
<td>4</td>
<td>110031</td>
<td>Power supply cable 15m</td>
</tr>
<tr>
<td>4</td>
<td>110132</td>
<td>Power supply cable 15m-MultiLink</td>
</tr>
<tr>
<td>5</td>
<td>110029</td>
<td>Inductive switch cable 2,5m</td>
</tr>
<tr>
<td>6</td>
<td>130007</td>
<td>Inductive switch cable 0,5m</td>
</tr>
<tr>
<td>7</td>
<td>130017</td>
<td>Inductive switch</td>
</tr>
<tr>
<td>8</td>
<td>130015</td>
<td>Holder for inductive switch</td>
</tr>
<tr>
<td>9</td>
<td>130022</td>
<td>Indicator for inductive switch</td>
</tr>
<tr>
<td>10</td>
<td>110077</td>
<td>Cup square neck bolt DIN603 8.8-M10x25 galvanized</td>
</tr>
<tr>
<td>11</td>
<td>110080</td>
<td>Spring washer DIN137B M10 waved, galvanized</td>
</tr>
<tr>
<td>12</td>
<td>110078</td>
<td>Hexagon nut DIN982 Kl.8 M10 galvanized</td>
</tr>
<tr>
<td>13</td>
<td>110075</td>
<td>Hexagon head screw DIN933 8.8-M10x35 galvanized</td>
</tr>
<tr>
<td>14</td>
<td>110079</td>
<td>Spring washer DIN137A M8 galvanized</td>
</tr>
<tr>
<td>15</td>
<td>110075</td>
<td>Hexagon socket head cap screw DIN912 -M8x20 galvanized</td>
</tr>
<tr>
<td>16</td>
<td>110143</td>
<td>Large diameter washer 8,4x30x1,5 A2, stainless</td>
</tr>
<tr>
<td>17</td>
<td>140000</td>
<td>Mobile Handheld</td>
</tr>
<tr>
<td>18</td>
<td>140007</td>
<td>Car-USB-Charger for Handheld 12V und 24V</td>
</tr>
<tr>
<td>19</td>
<td>140001</td>
<td>Bluetooth thermo printer</td>
</tr>
<tr>
<td>20</td>
<td>120008</td>
<td>Paper roll for printer</td>
</tr>
<tr>
<td>21</td>
<td>130019</td>
<td>DC/DC converter 12V -&gt; 24V</td>
</tr>
<tr>
<td>22</td>
<td>130020</td>
<td>AC/DC converter 230V -&gt; 24V</td>
</tr>
<tr>
<td>23</td>
<td>110081</td>
<td>User manual</td>
</tr>
</tbody>
</table>

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12 Connector & Cable Configurations

12.1 Power supply connector on Sensor

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Signal direction</th>
<th>Signal Info</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Power supply 0 VDC (GND)</td>
<td>GND</td>
<td>GND internal connected to housing via reverse battery protection diode</td>
</tr>
<tr>
<td>2</td>
<td>Power supply +24 VDC</td>
<td>input</td>
<td>+24VDC +/- 20%, Imax = 3.5A</td>
</tr>
<tr>
<td>N</td>
<td>Not connected</td>
<td>n.c.</td>
<td>n.c.</td>
</tr>
<tr>
<td>4</td>
<td>RS-422 / Bluetooth mode selector</td>
<td>input</td>
<td>“high” +24 VDC = RS-422 mode “low” 0V = Bluetooth mode</td>
</tr>
<tr>
<td>5</td>
<td>RS-422 sensor out -</td>
<td>differential output</td>
<td>Use only in RS-422 mode</td>
</tr>
<tr>
<td>N</td>
<td>RS-422 sensor out +</td>
<td>differential output</td>
<td>Use only in RS-422 mode</td>
</tr>
<tr>
<td>7</td>
<td>RS-422 sensor in +</td>
<td>differential input</td>
<td>Use only in RS-422 mode</td>
</tr>
<tr>
<td>½</td>
<td>RS-422 sensor in -</td>
<td>differential input</td>
<td>Use only in RS-422 mode</td>
</tr>
</tbody>
</table>

12.2 Inductive switch connector on Sensor

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Signal direction</th>
<th>Signal Info</th>
</tr>
</thead>
<tbody>
<tr>
<td>L</td>
<td>+12 VDC</td>
<td>out</td>
<td>Power supply inductive switch</td>
</tr>
<tr>
<td>N</td>
<td>Signal</td>
<td>in</td>
<td>Signal receive from inductive switch</td>
</tr>
<tr>
<td>½</td>
<td>0 VDC</td>
<td>out</td>
<td>Power supply inductive switch</td>
</tr>
</tbody>
</table>

12.3 Power supply cable 2.5m

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Lead color</th>
<th>Pin #</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>0 VDC (GND)</td>
<td>blue</td>
<td>2</td>
</tr>
<tr>
<td>2</td>
<td>+24 VDC</td>
<td>brown</td>
<td>1</td>
</tr>
<tr>
<td>N</td>
<td>Not connected</td>
<td></td>
<td>PE</td>
</tr>
<tr>
<td>4</td>
<td>Not connected</td>
<td></td>
<td></td>
</tr>
<tr>
<td>5</td>
<td>Not connected</td>
<td></td>
<td></td>
</tr>
</tbody>
</table>
12.4 Power supply cable 15m

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Lead color</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+24 VDC</td>
<td>brown</td>
</tr>
<tr>
<td>2</td>
<td>0 VDC (GND)</td>
<td>blue</td>
</tr>
<tr>
<td>PE</td>
<td>Not connected</td>
<td></td>
</tr>
</tbody>
</table>

12.5 Inductive switch cable 2.5m

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Lead color</th>
</tr>
</thead>
<tbody>
<tr>
<td>L</td>
<td>+12 VDC</td>
<td>Brown</td>
</tr>
<tr>
<td></td>
<td>0 VDC</td>
<td>White</td>
</tr>
<tr>
<td>N</td>
<td>Signal</td>
<td>Yellow</td>
</tr>
<tr>
<td></td>
<td>Not connected</td>
<td>PE</td>
</tr>
</tbody>
</table>

12.6 Inductive switch cable 0.5m

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Lead color</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+12 VDC</td>
<td>Brown</td>
</tr>
<tr>
<td>2</td>
<td>0 VDC</td>
<td>Blue</td>
</tr>
<tr>
<td>3</td>
<td>Signal</td>
<td>Black</td>
</tr>
<tr>
<td>PE</td>
<td>Not connected</td>
<td></td>
</tr>
</tbody>
</table>
### 12.7 Inductive switch

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>+12 VDC</td>
</tr>
<tr>
<td>2</td>
<td>0 VDC</td>
</tr>
<tr>
<td>3</td>
<td>Not connected</td>
</tr>
<tr>
<td>4</td>
<td>Signal</td>
</tr>
</tbody>
</table>

### 12.8 Data cable 3m

<table>
<thead>
<tr>
<th>Pin #</th>
<th>Signal</th>
<th>Signal direction</th>
<th>Signal Info</th>
<th>Lead color</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>Power supply 0 VDC</td>
<td>GND</td>
<td>GND internal connected to housing via reverse battery protection diode</td>
<td>Grown &amp; white</td>
</tr>
<tr>
<td></td>
<td>(GND)</td>
<td></td>
<td></td>
<td></td>
</tr>
<tr>
<td>2</td>
<td>Power supply +24 VDC</td>
<td>Input</td>
<td>+24VDC ± 20%, Imax = 3.5A</td>
<td>red</td>
</tr>
<tr>
<td>L</td>
<td>Not connected</td>
<td>n.c.</td>
<td></td>
<td>n.c.</td>
</tr>
<tr>
<td>4</td>
<td>RS-422 / Bluetooth mode selector</td>
<td>Input</td>
<td>“high” +24 VDC = RS-422 mode “low” 0V = Bluetooth mode</td>
<td>blue</td>
</tr>
<tr>
<td>5</td>
<td>RS-422 sensor out -</td>
<td>Differential output</td>
<td>Use only in RS-422 mode</td>
<td>gray</td>
</tr>
<tr>
<td></td>
<td>RS-422 sensor out +</td>
<td>Differential output</td>
<td>Use only in RS-422 mode</td>
<td>pink</td>
</tr>
<tr>
<td>7</td>
<td>RS-422 sensor in +</td>
<td>Differential input</td>
<td>Use only in RS-422 mode</td>
<td>Green</td>
</tr>
<tr>
<td>½</td>
<td>RS-422 sensor in -</td>
<td>Differential input</td>
<td>Use only in RS-422 mode</td>
<td>yellow</td>
</tr>
</tbody>
</table>